

Lecture 2. Sufficient Dimensionality Reduction: Supervised PCA, LDA, and SIR

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Outline

Sufficient Dimensionality Reduction

PCA as Sufficient Dimensionality Reduction

Supervised PCA

Linear Discriminant Analysis

Sliced Inverse Regression

Localized SIR

Sufficient Dimensionality Reduction

Definition (Cook 2005)

A **sufficient dimension reduction** Γ ($\Gamma \in \mathbb{R}^{p \times d}$, $\Gamma^T \Gamma = I_d$) refers to the setting that the conditional distribution of $Y|X$ is the same as the distribution of $Y|\Gamma^T X$ for all X , i.e.

$$\mathbb{P}(Y|X) = \mathbb{P}(Y|\Gamma^T X).$$

- ▶ Example: in regression $Y = f(X, \varepsilon)$, for some unknown function f , sufficient dimensionality reduction implies that $Y = f(\Gamma^T X, \varepsilon)$.

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- ▶ Example: in regression $Y = f(X, \varepsilon)$, for some unknown function f , sufficient dimensionality reduction implies that $Y = f(\Gamma^T X, \varepsilon)$.
- ▶ Can you find Γ without knowing f ?
- ▶ Yes! Consider the inverse problem, with conditional distribution $\mathbb{P}(X|Y)$.

An Inverse Model

Example (Inverse model)

For each value in response variable y ,

$$X_y = \mu + \Gamma \nu_y + \varepsilon \quad (1)$$

where

- ▶ $X_y \in \mathbb{R}^p$,
- ▶ $\nu_y \in \mathbb{R}^d$, $d < p$,
- ▶ $\Gamma \in \mathbb{R}^{p \times d}$ such that $\Gamma^T \Gamma = I_d$,
- ▶ $\varepsilon \sim N_p(0, \sigma^2 I_p)$,
- ▶ assume $\sum_y \nu_y = 0$ for removing the degree of freedom in translation.

Sufficient Dimensionality Reduction

Lemma (Cook 2005)

Under the inverse model, $\mathbb{P}(Y|X) = \mathbb{P}(Y|\Gamma^T X)$, i.e. Γ is a sufficient dimensionality reduction.

Proof

- ▶ First, $X|(Y = y) \sim N_p(\mu + \Gamma\nu_y, \sigma^2 I_p)$.
- ▶ By Bayesian formula, we have for any f

$$\begin{aligned} f_{Y|X}(y|x) &\propto f_{X|Y}(x|y)f_Y(y) \\ &\propto \exp\left(-\frac{1}{2\sigma^2}\|x - \mu - \Gamma\nu_y\|^2\right) f_Y(y) \\ &\propto \exp\left(-\frac{1}{2\sigma^2}(\nu_y^T \nu_y - 2\nu_y^T \Gamma^T(x - \mu))\right) f_Y(y) \end{aligned}$$

where the last line is given by the orthogonality $\Gamma^T \Gamma = I$.

Proof (continued)

- ▶ Similarly, since $\Gamma^T X | (Y = y) \sim N_d(\Gamma^T \mu + \nu_y, \sigma^2 I_d)$, we have

$$\begin{aligned} f_{Y|\Gamma^T X}(y|\Gamma^T x) &\propto f_{\Gamma^T X|Y}(\Gamma^T x|y) f_Y(y) \\ &\propto \exp\left(-\frac{1}{2\sigma^2} \|\Gamma^T x - \Gamma^T \mu - \nu_y\|^2\right) f_Y(y) \\ &\propto \exp\left(-\frac{1}{2\sigma^2} (\nu_y^T \nu_y - 2\nu_y^T \Gamma^T (x - \mu))\right) f_Y(y) \end{aligned}$$

by the orthogonality $\Gamma^T \Gamma = I$.

- ▶ Therefore, $\mathbb{P}(Y|X) = \mathbb{P}(Y|\Gamma^T X)$ of the same density kernels. \square

Estimate of Γ

- ▶ Can we estimate Γ from finite sample without knowing f ?

Estimate of Γ

- ▶ Can we estimate Γ from finite sample without knowing f ?
- ▶ PCA gives the Maximum Likelihood Estimate of Γ

Maximum Likelihood Estimate

- ▶ Under the inverse model, the conditional likelihood function

$$f(X_y|\mu, \Gamma, \nu_y) = \frac{1}{\sigma^p \sqrt{(2\pi)^p}} \exp \left[-\frac{1}{2\sigma^2} (X_y - \mu - \Gamma\nu_y)^T (X_y - \mu - \Gamma\nu_y) \right]$$

- ▶ MLE

$$\begin{aligned} & \max_{\mu, \Gamma, \nu_y} \prod_y f(X_y|\mu, \Gamma, \nu_y) \\ \Leftrightarrow & \max_{\mu, \Gamma, \nu_y} -\frac{1}{2\sigma^2} \sum_y \|X_y - \mu - \Gamma\nu_y\|^2 - \sum_y p \log \sigma + C. \end{aligned}$$

Maximum Likelihood Estimate (continued)

- ▶ MLE solution

$$\hat{\Gamma} = \arg \min_{\Gamma^T \Gamma = I} \sum_y \|X_y - \hat{\mu} - P_{\Gamma}(X_y - \hat{\mu})\|^2, \quad P_{\Gamma} = \Gamma \Gamma^T. \quad (2)$$

where $\hat{\mu} = \frac{1}{n} \sum_y X_y$, $\nu_y = \hat{\Gamma}^T (X_y - \hat{\mu})$.

- ▶ If y is of distinct values (e.g. the unknown f is injective), PCA (top d eigen-decomposition of $\hat{\Sigma}$) gives $\hat{\Gamma}$.
- ▶ If y is of discrete values (e.g. classification), discriminant analysis (eigen-decomposition of $\hat{\Sigma}_B = \frac{1}{K} \sum_{y=1}^K (\hat{\mu}_y - \hat{\mu})(\hat{\mu}_y - \hat{\mu})^T$) gives $\hat{\Gamma}$.

Maximum Likelihood Estimate (continued)

- ▶ In general

$$X_y = \mu + \Gamma \nu_y + \epsilon \quad (3)$$

where $\epsilon \sim N_p(0, \Sigma)$, $\hat{\mu}_y = \hat{E}[X_y|y]$.

- ▶ Rescale $Z_y = \Sigma^{-1/2} X_y$.
- ▶ Eigen-decomposition of $\Sigma^{-1/2} \hat{\Sigma}_B \Sigma^{-1/2}$ (with $\hat{\Sigma}$ for the estimate of Σ) meets Fisher's Linear Discriminant Analysis for $\hat{\Gamma}$.
- ▶ Therefore *PCA/LDA can be also derived as a sufficient dimensionality reduction in supervised learning, even the function f is unknown here.*

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Linear Discriminant Analysis

- ▶ Data: $\{X_i, y_i\}_{i=1}^N$ where y_i is discrete in $\{1, 2, \dots, K\}$ but not ordered
- ▶ Compute sample mean and within class means

$$\hat{\mu} = \frac{1}{N} \sum_{i=1}^N X_i, \quad \hat{\mu}_k = \frac{1}{N_k} \sum_{y_i=k} X_i;$$

- ▶ Compute Between class covariance matrix

$$\hat{\Sigma}_B^{p \times p} = \frac{1}{K} \sum_{k=1}^K (\hat{\mu}_k - \hat{\mu})(\hat{\mu}_k - \hat{\mu})^T;$$

- ▶ Compute Within class covariance matrix

$$\hat{\Sigma}_W^{p \times p} = \frac{1}{N - K} \sum_{k=1}^K \sum_{y_i=k} (X_i - \hat{\mu}_k)(X_i - \hat{\mu}_k)^T;$$

Fisher's Linear Discriminant Analysis

We choose the k -th class such that the following *linear* score function is the largest:

$$\hat{\delta}_k(x) = \hat{\mu}_k^T \hat{\Sigma}^{-1} x - \frac{1}{2} \hat{\mu}_k^T \hat{\Sigma}^{-1} \hat{\mu}_k + \log \hat{\pi}_k, \quad (4)$$

where given data $(x_i, y_i), i = 1, \dots, n$,

- ▶ $\hat{\pi}_k = n_k/n$ is the sample proportion of class k where n_k is the number of subjects in class k
- ▶ $\hat{\mu}_k$ is the sample mean of class k

$$\hat{\mu}_k = \frac{1}{n_k} \sum_{i:y_i=k} x_i;$$

- ▶ $\hat{\Sigma}$ is the pooled (overall) sample covariance

$$\hat{\Sigma} = \hat{\Sigma}_B + \hat{\Sigma}_W = \frac{1}{n - K} \sum_{k=1}^K \sum_{i:y_i=k} (x_i - \hat{\mu}_k)(x_i - \hat{\mu}_k)^T,$$

Fisher's LDA

- ▶ Fisher's LDA (1920s) aims to capture dominant variations between different classes of data:
 - Compute **generalized Eigen-decomposition** $\hat{\Sigma}_B = \hat{\Sigma}U\Lambda U^T$ with $\Lambda = \mathbf{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$;
 - Choose top- d generalized eigenvectors corresponding to top $d \leq K$ nonzero eigenvalues,

$$U_d = [u_1, \dots, u_d], \quad u_j \in \mathbb{R}^p.$$

Sliced Inverse Regression

- ▶ Data: $\{X_i, y_i\}_{i=1}^N$, where $X_i \in \mathbb{R}^p$, $y_i \in \mathbb{R}$ is continuous (or ordered discrete)
- ▶ Divide the range of y_i into S non-overlapping slices H_s ($s = 1, \dots, S$). N_s is the number of observations within each slice.
- ▶ Compute the sample mean and total covariance matrix

$$\hat{\mu} = \frac{1}{N} \sum_{i=1}^N X_i, \quad \hat{\Sigma}^{p \times p} = \frac{1}{N} \sum_{i=1}^N (X_i - \hat{\mu})(X_i - \hat{\mu})^T;$$

- ▶ Compute the mean of X_i over all slices and Between slices covariance matrix

$$\hat{\mu}_k = \frac{1}{N_s} \sum_{y_i \in H_s} X_i, \quad \hat{\Sigma}_B^{p \times p} = \frac{1}{K} \sum_{k=1}^K (\hat{\mu}_k - \hat{\mu})(\hat{\mu}_k - \hat{\mu})^T;$$

Li's SIR

- ▶ K.-C. Li's Slice Inverse Regression (1991) aims to capture dominant variations between different slices of data:
 - Compute **Generalized Eigen-decomposition** $\hat{\Sigma}_B = \hat{\Sigma}U\Lambda U^T$ with $\Lambda = \mathbf{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$;
 - Choose top- d generalized eigenvectors corresponding to top $d \leq K$ nonzero eigenvalues,

$$\Gamma_d = [u_1, \dots, u_d], \quad u_k \in \mathbb{R}^p.$$

Localized Sliced Inverse Regression

- ▶ Data: $\{X_i, y_i\}_{i=1}^N$, where $X_i \in \mathbb{R}^p$, $y_i \in \mathbb{R}$ is continuous (or ordered discrete)
- ▶ Divide the range of y_i into S non-overlapping slices $H_s (s = 1, \dots, S)$. N_s is the number of observations within each slice.
- ▶ Compute the sample mean $(\hat{\mu})$ and total covariance $\hat{\Sigma}$ as in SIR
- ▶ Compute the **localized** mean of X_i over all slices and **localized** Between-slice covariance matrix

$$\hat{\mu}_{i,loc} = \frac{1}{|s_i|} \sum_{j \in s_i} X_j, \quad \hat{\Sigma}_{locB} = \frac{1}{N} \sum_i (\hat{\mu}_{i,loc} - \hat{\mu})(\hat{\mu}_{i,loc} - \hat{\mu})^T ;$$

where $s_i = \{j : x_j \text{ belongs to the } k \text{ nearest neighbours of } x_i \text{ in } H_s\}$ and s indexes the slice H_s to which i belongs.

LSIR

- ▶ Wu-Liang-Mukherjee Localized Slice Inverse Regression (2009) aims to capture nonlinear variations between different slices of data:
 - Compute **Generalized Eigen-decomposition** $\hat{\Sigma}_{locB} = \hat{\Sigma}U\Lambda U^T$ with $\Lambda = \mathbf{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$ where $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$;
 - Choose top- d generalized eigenvectors corresponding to top $d \leq K$ nonzero eigenvalues,

$$\Gamma_d = [u_1, \dots, u_d], \quad u_k \in \mathbb{R}^p.$$