

# Identity Management on Homogeneous Spaces

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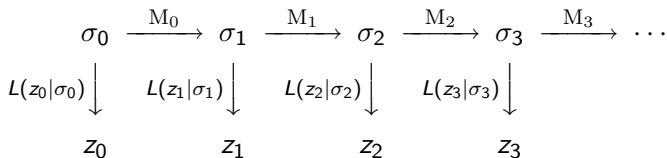
# Problem in Identity Management



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# Markov Model for Identity Management



$\sigma$ : true state;  $z$ : observations;  $M$ : markov matrix;  $L(z|\sigma)$ : likelihood function.

- Mixing Model: tracks swapped identities with some probability.
- Observation Model: identity on a particular track is observed.
- Problem: For each timestep, find posterior over  $\sigma_t$  conditioned on all past observations.
- **Our Problem:** Find posterior over **class characteristics** (red or blue) conditioned on all past observations.

# Our Problem

- Define  $\sigma^{(t)} \in S_n$  to be a mapping from identities  $\{i_1, i_2, \dots, i_{m+n}\}$  to tracks  $T = \{t_1, t_2, \dots, t_{m+n}\}$ .
- After a random permutation among tracks  $\tau^{(t)}$ . The association of identities with tracks at time  $t + 1$  is  $\sigma^{(t+1)} = \tau^{(t)}\sigma^{(t)}$ .
- Assume  $n$  of the identities are red and the remaining  $m$  identities are blue.
- We care only about the **class characteristics** (red or blue) of identities.

# Homogeneous Space

- **Homogeneous Space:** All  $k$ -subsets of  $\{1, 2, \dots, n\}$ .
- Permutation groups act on homogeneous spaces.

## Example

- Suppose  $n = 3, k = 2$ , homogeneous space  $X$  is all 2-subset of  $\{1, 2, 3\}$ , i.e.  $X = \{\{1, 2\}, \{2, 3\}, \{1, 3\}\}$ .
- Permutation group  $S_3$  acts on  $X$ , e.g., if

$$\tau = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

then  $\tau(\{1, 2\}) = \{2, 3\}$ ;  $\tau(\{2, 3\}) = \{1, 3\}$ ;  $\tau(\{1, 3\}) = \{1, 2\}$ .

# Markov Process on Homogeneous Space

- A probability distribution  $Q$  on permutation groups induces a Markov process on the homogeneous space  $X$  with transition probability

$$P_x(y) = \sum_{\tau: \tau x = y} Q(\tau)$$

- **Naive Model:** Maintain beliefs on homogeneous space instead of full permutation group.

# Running Example

## Example (Markov Model on Homogeneous Space)

- Suppose  $m = n = 3$  and we are sure that  $\{t_1, t_2, t_3\}$  are red, then  $f \in L(X)$

$$f(x) = \begin{cases} 1 & \text{if } x = \{t_1, t_2, t_3\} \\ 0 & \text{otherwise} \end{cases}$$

- If a mixing happened among tracks  $t_3$  and  $t_4$ , then

$$Q(\tau) = \begin{cases} p & \tau = \text{id} \\ 1 - p & \tau = (t_3, t_4) \\ 0 & \text{otherwise} \end{cases}$$

- The Markov mixing matrix induced from  $Q$  would be

	$\{t_1, t_2, t_3\}$	$\{t_1, t_2, t_4\}$	$\{t_1, t_2, t_5\}$	$\dots$	$\{t_3, t_5, t_6\}$	$\{t_4, t_5, t_6\}$
$\{t_1, t_2, t_3\}$	$p$	$1 - p$	0	$\dots$	0	0
$\{t_1, t_2, t_4\}$	$1 - p$	$p$	0	$\dots$	0	0
$\{t_1, t_2, t_5\}$	0	0	1	$\dots$	0	0
$\vdots$	$\vdots$	$\vdots$	$\vdots$	$\ddots$	$\vdots$	$\vdots$
$\{t_3, t_5, t_6\}$	0	0	0	$\dots$	$p$	$1 - p$
$\{t_4, t_5, t_6\}$	0	0	0	$\dots$	$1 - p$	$p$



# Mixing Model

- Suppose  $Q$  is a distribution on permutation group  $S_{m+n}$ , then the simplest mixing model is

$$Q(\tau) = \begin{cases} p & \tau = \text{id} \\ 1 - p & \tau = (t_i, t_j) \\ 0 & \text{otherwise} \end{cases}$$

- $Q$  induces a Markov update of beliefs for  $f \in L(X)$

$$f(y) \leftarrow \sum_x P_x(y) f(x)$$

where  $P_x(y) = \sum_{\tau: \tau x = y} Q(\tau)$ .

# Observation Model

- The simplest model for observation consist of receiving information  $z$  that with some high probability, target on track  $t_i$  is red.
- Likelihood function have the form ( $a \gg b$ ):

$$L(z|x) = \begin{cases} a & \text{if } t_i \in x \\ b & \text{if } t_i \notin x \end{cases}$$

- Posterior by Bayes rule

$$f(x|z) = \frac{L(z|x) \cdot f(x)}{\sum_x L(z|x) \cdot f(x)}$$

# Decomposition of Homogeneous Space

- Function space of homogeneous space  $M^{m,n}$  decomposes as

$$S^{m+n} \oplus S^{m+n-1,1} \oplus S^{m+n-2,2} \oplus \dots \oplus S^{m,n}$$

- $S^{m+n-i,i}$  is invariant under actions by  $S_{m+n}$ .
- **Hierarchical structures:** Direct sum of the first  $j$  subspaces is a  $\binom{m+n}{j}$  dimensional subspace, can be regarded as functions defined on all  $j$ -subsets ( $j^{\text{th}}$  order statistics).
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$$\begin{aligned} M^{m,n} &= S^{m+n} \oplus S^{m+n-1,1} \oplus S^{m+n-2,2} \oplus \dots \oplus S^{m,n} \\ &= M^{m+n-j,j} \oplus S^{m+n-j-1,j+1} \oplus \dots \oplus S^{m,n} \end{aligned}$$

- ▶  $M^{m,n}$ : all  $n$ -subsets of  $\{1, 2, \dots, m+n\}$ .
- ▶  $M^{m+n-j,j}$ : all  $j$ -subsets of  $\{1, 2, \dots, m+n\}$ .

# Radon Up Transformations

- For  $1 \leq k \leq n$  define the *Radon up transform*

$$R^+ : M^{m+n-k,k} \rightarrow M^{m,n} \quad \text{by} \quad R^+ f(s) = \sum_{s \supset r} f(r)$$

where  $r \in M^{m+n-k,k}$  is a  $k$ -subset and  $s \in M^{m,n}$  is an  $n$ -subset.

## Example

- Suppose  $f^2 \in M^{4,2}$  is

$\{t_1, t_2\}$	$\{t_1, t_3\}$	$\{t_2, t_3\}$	$\{t_1, t_4\}$	$\cdots$	$\{t_4, t_6\}$	$\{t_5, t_6\}$
4	4	4	2	$\cdots$	0	0

- After Radon transformation,  $f^3 = R_{2,3}^+ f^2$  would be

$\{t_1, t_2, t_3\}$	$\{t_1, t_2, t_4\}$	$\{t_1, t_4, t_5\}$	$\cdots$	$\{t_4, t_5, t_6\}$
4+4+4	4+2+2	2+2+0	$\cdots$	0+0+0

# Radon Down Transformations

- If  $M^{m,n}$  and  $M^{m+n-k,k}$  are given bases consisting of delta functions on  $n$ -subsets and  $k$ -subsets. For  $1 \leq k \leq n$  define *Radon down transform*  $R^- : M^{m,n} \rightarrow M^{m+n-k,k}$ , the  $(r, s)$  element of  $R^-$  is

$$\frac{(-1)^{n-k}(n-k)}{(-1)^{|s-r|}|s-r|\binom{m+n-k}{|s-r|}}$$

where  $r \in M^{m+n-k,k}$  is a  $k$ -subset and  $s \in M^{m,n}$  is an  $n$ -subset.

- Radon transform  $R^+$  and  $R^-$  satisfy
  - ▶  $R^- R^+ = I$
  - ▶  $R^+ R^-$  is an orthogonal projection.

## Bandlimited Mixing Model

- **Bandlimiting:** Maintain  $k^{\text{th}}$  order statistics  $f^k \in M^{m+n-k,k}$ , which can be interpreted as the likelihood of a particular  $k$ -subset being all red.
- Induce mixing model  $Q$  to  $M^{m+n-k,k}$  and update  $f^k$  by

$$f^k(y) \leftarrow \sum_x P_x(y) f^k(x)$$

$$\begin{array}{ccccccc}
 f_0^n & \xrightarrow{M_0^n} & f_1^n & \xrightarrow{M_1^n} & f_2^n & \xrightarrow{M_2^n} & f_3^n & \xrightarrow{M_3^n} & \dots \\
 R_{n,k}^- \downarrow & & R_{n,k}^- \downarrow & & R_{n,k}^- \downarrow & & R_{n,k}^- \downarrow & & \\
 f_0^k & \xrightarrow{M_0^k} & f_1^k & \xrightarrow{M_1^k} & f_2^k & \xrightarrow{M_2^k} & f_3^k & \xrightarrow{M_3^k} & \dots
 \end{array}$$

### Theorem

Both  $R^+$  and  $R^-$  commute with the Markov mixing matrices induced from probability  $Q$  on permutation group  $S_{m+n}$ .

# Bandlimited Observation Model

- Observation consists of first order statistics (observing the identity on track  $t_i$  is red with high probability)
- Lift first order statistics to  $k^{th}$  order statistics by Radon up transform.
- Use Bayes update to get posterior.

# Classification Criteria

- We project  $k^{th}$  order statistics to first order statistics using Radon down transform.
- Predict the tracks with highest  $n$  scores as red members.



# Real Camera Data

- Real Network with 8 Cameras
- 11 People (5 red, 6 blue)
- Experiments with different number of mixing events and observation events

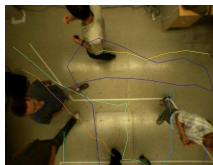


Figure: Sample Image.

Table: Experiments Data Summary

Experiment	#Mixings	#Observations	Explanations
1	8	76	few mix, lots of obs
2	169	184	
3	226	116	
4	261	64	lots of mix, few obs

# Energy Distributions

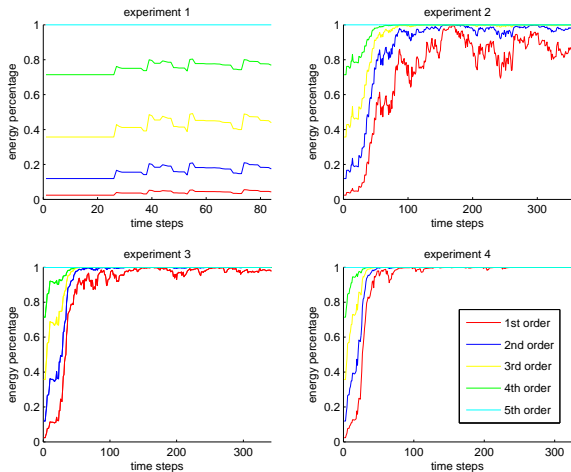


Figure: Energy distributions for four experiments

# Classification Accuracy

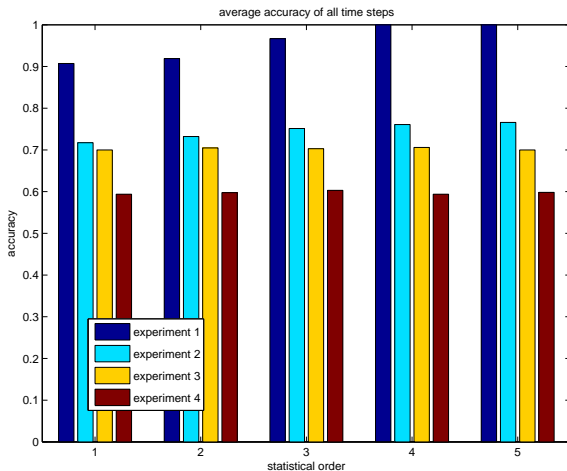


Figure: Classification accuracy of implementation with different statistical order.

# Conclusions and Future Work

## Conclusions

- Distributions on homogeneous spaces can be compactly summarized.
- Radon transforms useful for mapping distributions between different statistical orders.
- Evaluation of our model on a real camera network.

## Future

- Use similar ideas to study other machine learning problems arising from ranking and voting.
- Smarter ways of projecting data on homogeneous spaces to low order statistics.